## Registers

Register is a set of FFs connected in such a way as to load serial or/and parallel data and store it.

## Parallel Registers:

## Example:

Design a 3 bit parallel in-parallel out register of 3-bit register.

One part of the parallel Load register:
INPUTS: Output= Q
L= Load
I =Input
When Load $=1$ then data I , is loaded to the register
When Load=0 the value of Q is loaded in the register.
The following state diagram is then derived where input $\mathbf{L}, \mathbf{I}$


Translate into state transition table

| Q | $\mathrm{LI}=00$ | L <br> $\mathrm{I}=01$ | $\mathrm{~L}=11$ | $\mathrm{~L} \mathrm{I}=10$ |  |
| :--- | :---: | :---: | :---: | :--- | :--- |
| 0 | 0 | 0 | 1 | 0 |  |
| 1 | 1 | 1 | 1 | 0 |  |
|  |  |  |  |  |  |

$\mathrm{Q}+=\mathrm{L}^{\prime} \mathrm{Q}+\mathrm{L} \mathrm{I}$ which is MUX equation
using a D-Flip Flop, $\mathrm{Q}+=\mathrm{D}==\mathrm{L}$ ' $\mathrm{Q}+\mathrm{L}$ I


Now have multiple of the design as many bits as you like. Below is 3-bit parallel register designed with the above method.


## Parallel In-Parallel Out register.



## An 8-bit register



## Symbols



FlipFlop Simulation
Now: 2200 ns
81 clk
81 clr
onload
8nd
819


## Symbol Of 8-bit parallel load/ parallel out register



Example: Design a 3-bit L->R shift register.

## $\rightarrow \rightarrow$

$000 \mathrm{x}=1=>100 \quad \mathrm{x}=0=>000$
$2^{3}$ states


| Present state |  |  | Next state |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{y}_{2}$ | $\mathrm{y}_{1}$ | $\mathrm{y}_{0}$ | $\mathrm{y}_{2}{ }^{+}$ | $\mathrm{y}_{1}{ }^{+}$ | $\mathrm{y}_{0}{ }^{+}$ | $\mathrm{y}_{2}{ }^{+}$ | $\mathrm{y}_{1}^{+}$ | $\mathrm{y}_{0}{ }^{+}$ |  |
| 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 |  |
| 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 |  |
| 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 |  |
| 0 | 1 | 1 | 1 | 0 | 1 | 0 | 0 | 1 |  |
| 1 | 0 | 0 | 1 | 1 | 0 | 0 | 1 | 0 |  |
| 1 | 0 | 1 | 1 | 1 | 0 | 0 | 1 | 0 |  |
| 1 | 1 | 0 | 1 | 1 | 1 | 0 | 1 | 1 |  |
| 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 |  |

For registers it is customary to use D-FFs. Therefore, using D-FFs for the above table: $\mathrm{D}_{2}=\mathrm{y}_{2}^{+} ; \mathrm{D}_{1}=\mathrm{y}_{1}^{+} ; \mathrm{D}_{0}=\mathrm{y}_{0}^{+}$.


## Example 2.

Design 3-bit left-to-right and right-to-left shift register
Control signal:
$\mathrm{C}=1: \mathrm{L} \rightarrow \mathrm{R}$
$\mathrm{C}=0: \mathrm{R} \rightarrow \mathrm{L}$


From the state diagram we will fill the state table out and follow standard implementation procedure.

| Present state |  |  | Next state |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | $\mathrm{C}=1(\mathrm{~L} \rightarrow \mathrm{R})$ |  |  |  |  |  | $\mathrm{C}=0$ ( $\mathrm{H} \rightarrow \mathrm{L}$ ) |  |  |  |  |  |
|  |  |  | $\mathrm{x}=1$ |  |  | $\mathrm{x}=0$ |  |  | $\mathrm{x}=1$ |  |  | $\mathrm{x}=0$ |  |  |
| $\mathrm{y}_{2}$ | $\mathrm{y}_{1}$ | $\mathrm{y}_{0}$ | $\mathrm{y}_{2}{ }^{+}$ | $\mathrm{y}_{1}{ }^{+}$ | $\mathrm{y}_{0}{ }^{+}$ | $\mathrm{y}_{2}{ }^{+}$ | $\mathrm{y}_{1}{ }^{+}$ | $\mathrm{y}_{0}{ }^{+}$ | $\mathrm{y}_{2}{ }^{+}$ | $\mathrm{y}_{1}{ }^{+}$ | $\mathrm{y}_{0}{ }^{+}$ | $\mathrm{y}_{2}{ }^{+}$ | $\mathrm{y}_{1}{ }^{+}$ | yo |
| 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 |
| 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 1 | 0 |
| 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | 0 | 1 | 1 | 0 | 0 |
| 0 | 1 | 1 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| 1 | 0 | 0 | 1 | 1 | 0 | 0 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | 0 |
| 1 | 0 | 1 | 1 | 1 | 0 | 0 | 1 | 0 | 0 | 1 | 1 | 0 | 1 | 0 |
| 1 | 1 | 0 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | 0 | 1 | 1 | 0 | 0 |
| 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| $\begin{aligned} & y_{2}^{+}=C x+C^{\prime} y_{1} \\ & y 1=C y_{2}+C^{\prime} y_{0} \\ & y_{0}=C^{\prime} y_{1}+C^{\prime} x \end{aligned}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |



## Other counters

## BCD Counter:

0-1-2-3-4-5-6-7-8-9-0-1-...

| Present state | Next state |
| :---: | :---: |
| 0000 | 0001 |
| 0001 | 0010 |
| 0010 | 0011 |
| 0011 | 0100 |
| 0100 | 0101 |
| 0101 | 0110 |
| 0110 | 0111 |
| 0111 | 1000 |
| 1000 | 1001 |
| 1001 | 0000 |
| x | x |

## Ring counter

0001
1000
0100
0010
0001
1000


$=========$ General information for interested students===================

## Symbols



FlipFlop Simulation
Now:
2200 ns
80 clk
87 clr
8 lload
3 Al
819


## Symbol Of 8-bit parallel load/ parallel out register



## Simulation of some of the registers:

The 8-bit parallel load shift register is composed of multiplexers and D flip-flops, refer to figure. The multiplexers select whether to load the data or to simply pass the previous register value. If neither the load or shift enable inputs are high the registers keep their current values. If both inputs are high then the load input takes precedence. Otherwise the circuit either loads or shifts at each clock cycle with respect to the input that is high. If the circuit is shifting then a 0 is introduced at the leftmost bit.


Figure Parallel Load Shift Register.
The result of simulating the circuit is shown in figure below.


Figure Parallel Load Shift Register Simulation.

## Parallel Load Parallel Output Register

Similar to the previous register, the parallel load parallel output register is composed of multiplexers and D flip-flops. In this case, however, the circuit either loads new data or does not change its output. Refer to figure below for the schematic.


Figure Parallel Load Parallel Output Register.
The result of simulating the circuit is shown in figure below.


Figure Parallel Load Parallel Output Register Simulation.

## Serial-Input Parallel Output Register

The final register circuit in the multiplier is the serial-input parallel output register. This register stores the result of each succeeding column addition and outputs the result in parallel. The circuit is very similar to the other two registers however it is configured to shift a data bit into the MSB and to output the register state when it is not shifting data as shown in its 8 -bit implementation below.


Figure Serial-Input Parallel Output Register.
The result of simulating the circuit is shown in figure below.


Figure Serial-Input Parallel Output Register Simulation.

